Improvement Theory A Retrospective

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With thanks to former co-authors Andy Moran and Jörgen Gustavsson

Pure Functional Programming

...is cool because there are many natural observational equivalences between programs

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a + b ≅ b + a
tail(h:t) ≅ t
LHS ≅ RHS
```

and we can use these *anywhere* in a program to obtain an equivalent program

Equivalence is nice



Equivalence is nice



Problem 1



It's all the same to equivalence

but some programs are "more equal than others"

Problem 1: Example

If we replace a + b with b + a then surely nothing bad could happen... could it?

- Time complexity?
 cannot change
- Space complexity?
 asymptotic speedup or slowdown possible!

Problem 2

 $t \simeq tail (h:t)$

RHS ≃ LHS

Replacing equals by equals is fool-proof ...isn't it?

repeat :: a -> [a]
repeat x = x : repeat x

RHS \cong x : tail (x : repeat x) \cong x : tail (repeat x)

repeat x = x : tail (repeat x)

Improvement Theory

 Improvement Theory developed to solve problem (making sure that optimisations never make things worse, no matter what)

 Surprisingly, improvement theory provides a solution to problem

A Taster

A brief taste from a heap of papers about improvement

- Improvement Theory
- Correctness of Program Transformation by Improvement
- Reasoning about Improvement: The tick algebra
- Space Improvement

From Equivalence to Improvement

When are two programs equivalent?

Observational Equivalence

P and Q are observationally equivalent, $P \cong Q$ iff

in whatever program context we use them, they yield the same observable outcome:

 $\forall C[.]. obs(C[P]) = obs(C[Q])$

Defined using an operational semantics

Improvement (Time)

Program phrase P is **improved by** Q, $P \triangleright Q$ iff $P \cong Q$ and in whatever program context we use them, Q is never slower than P $\forall C[.]. time(C[P]) \geq time(C[Q])$ **Defined using** an operational

semantics

Also studied an asymptotic definition. Not in this talk

Problem 2, stated more precisely

The following proof rule is sound

$$\frac{P \cong Q}{\text{et } x = P \text{ in } x \cong \text{let } x = Q \text{ in } x}$$

It does **not** justify the bad transformation

Not true because r is a free variable

$$\frac{(\lambda \text{ x. x: r x}) \cong (\lambda \text{ x. x : tail (r x)})}{\text{let } r = (\lambda \text{ x. x: r x}) \cong \text{let } r = (\lambda \text{ x. x : tail (r x)})}$$

but does not allow any interesting program transformations either!

The Improvement Theorem

Sands, POPL'95 Total Correctness by Local Improvement...

In the informal transformation we used the unsound rule

 $\underline{\text{let } x = P \text{ in } P \cong \text{ let } x = P \text{ in } Q}$

let x = P in $x \cong$ let x = Q in x

The Improvement Theorem

let x = P in $P \triangleright$ let x = P in Q

let x = P in $x \triangleright$ let x = Q in x

The bad transformation is not justified because replacing RHS with LHS is not an improvement.

The Improvement Theorem

What's it good for?

- The first sound Unfold-Fold transformation method for functional programs [POPL'95]
- General correctness criteria for recursionmemoization-based program transformations [Sands, ESOP'95]
 - higher-order deforestation ["]
 - partial evaluation [Welinder, PhD'96]
 - supercompilation [Jonsson and Nordlander, POPL'09]
- A robust proof method insensitive to wacky language features [Lassen & Moran, MFCS'99]

The tick algebra: how reason with ⊳

Basic laws can be established (with some effort)

 $\mathsf{R}[\mathsf{case} \ \mathsf{b} \ \mathsf{of} \ \{\ldots \mathsf{pat}_i => a_i \ \ldots\}] \triangleleft \rhd \ \mathsf{case} \ \mathsf{b} \ \mathsf{of} \ \{\ldots \mathsf{pat}_i => \mathsf{R}[a_i] \ \ldots\}$

To enable equational reasoning such laws are used together with the **tick algebra**

- The tick (\checkmark) is a representation of a basic computation step (it is just the identity function)

LHS $\triangleleft \triangleright \checkmark RHS$ \checkmark (if B then P else Q) $\triangleleft \triangleright$ if B then $\checkmark P$ else $\checkmark Q$

Have we also Solved Problem 1?

 Not quite – so far we used a call-by-name computation model (easy to work with, but not resource-correct for Haskell)

> Moran & Sands, POPL'99 Improvement in a Lazy Context: An Operational Theory for Call-by-need

- A truly semantic theory for call-by-need
 - Subsumes call-by-need lambda calculus [Ariola, Maraist, Odersky, Felliesen, Wadler, POPL'95]
 - Shows that it can only speed-up programs by a constant factor!
 - Improvement theorem etc. etc.

Enter:

Space Improvement

Modest aim: when is a transformation guaranteed not to make space consumption worse by more than a constant factor $a + b \longrightarrow b + a$



Space Improvement

Two major problems ('99)

- are there *any* interesting space improvements?
- even if their are, will we be able to prove them?
- Key ingredients:
 - 1. A simple abstract machine (no graph nonsense) for modelling space
 - 2. A PhD student with a very big brain

Space Improvement

There are nontrivial space improvements!

E.g. Beta-var is a space improvement

 $(\lambda x.M) y \triangleright_s M[x := y]$

- To prove them we need to work with non asymptotic space improvement
- Developed fixedpoint induction principle
 - improvement theorem unsound for space
 - Example:

 $(xs ++ ys) ++zs \triangleleft \triangleright_s xs ++ (ys ++zs)$

but only if heap and stack are added!

Gustavsson & Sands, ICFP'01 Possibilities and Limitations of Call-by-need Space Improvement Never mind the ticks, make way for the space gadgets!

- Spikes short-lived local maxima in heap/stack usage
 ↓M ≡ case True of {True => M}
- Dummies

 ${}^{x}M \equiv \text{let } y = x \text{ in } M$ (y fresh)

- Weights: ⁿ_mM long lived extra heap usage
- **Baloons**: zero weights (handle with care!)

Conclusions

- Several uses for time improvement and the improvement theorem in particular
- No takers for space improvement – Need to make tools to make it easier to use?

f y x = x + y \longrightarrow $f y x = y \cdot seq \cdot x \cdot seq \cdot x + y$

