

Certifying homological algorithms to study biomedical images*

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- 2 Biomedical images and certified software
- 3 Reduction procedure
- 4 Methodology and experimental aspects
- 5 Conclusions and further work

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The Formath project

- European project
- Formath: Formalization of Mathematics

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 - Integration of Theorem Prover Tools
 - Representation of Simplicial Complexes
 - Certified Computation of Homology Groups
 - The Basic Perturbation Lemma
 - Applications to Medical Imagery

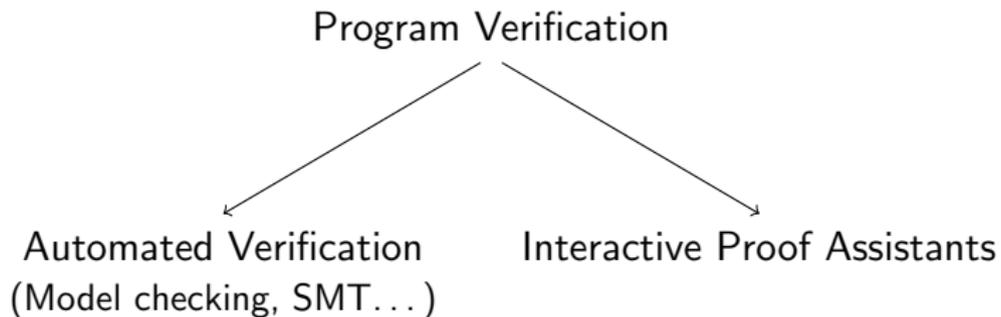
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Verification and Theorem prover tools



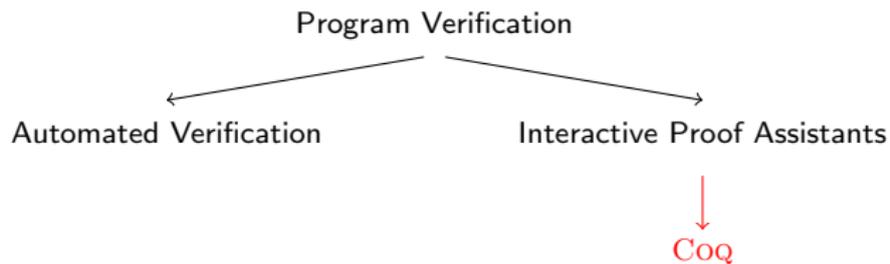
Interactive Proof Assistants

- What is an Interactive Proof Assistant?
 - Software tool for the development of formal proofs
 - Man-Machine collaboration:
 - Human: design the proofs
 - Machine: fill the gaps
 - Examples: Isabelle, HOL, ACL2, Coq...

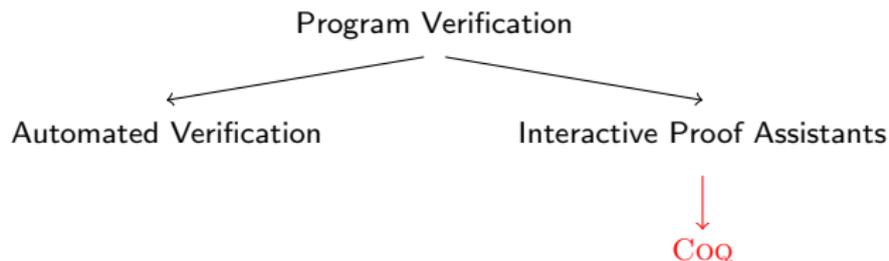
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 - Examples: Isabelle, HOL, ACL2, Coq...
- Applications
 - Mathematical proofs:
 - Four Color Theorem
 - Kepler Conjecture
 - Feit-Thompson Theorem (Odd Order Theorem)
 - ...
 - Software and Hardware verification:
 - C compiler
 - AMD5K86 microprocessor
 - ...

Coq/SSReflect



Coq/SSReflect

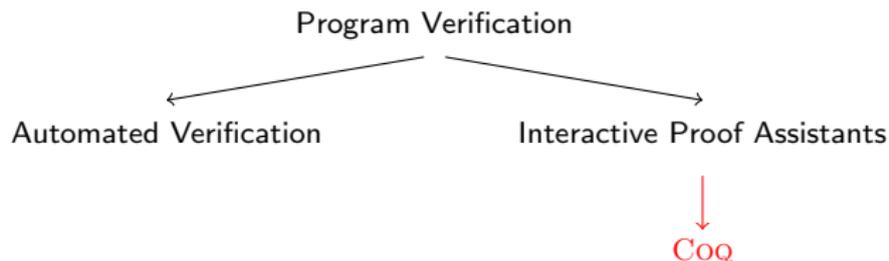


- Coq:
 - Based on Calculus of Inductive Constructions
 - Interesting feature: program extraction from a constructive proof



Y. Bertot and P. Castéran. *Interactive Theorem Proving and Program Development. Coq'Art: The Calculus of Inductive Constructions Series. Texts in Theoretical Computer Science. An EATCS Series*, 2004.

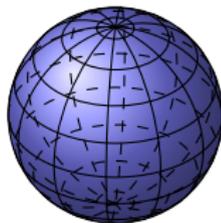
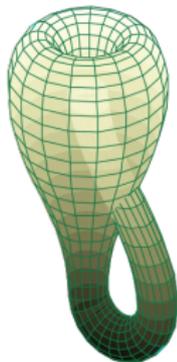
Coq/SSReflect



- Coq:
 - Based on Calculus of Inductive Constructions
 - Interesting feature: program extraction from a constructive proof
- SSReflect:
 - Extension of Coq
 - Developed while formalizing the Four Color Theorem by G. Gonthier
 - Used in the formalization of Feit-Thompson Theorem

Algebraic Topology

Topological Spaces \longrightarrow Invariant Groups

 H_0 H_1 \dots

Algebraic Topology

Topological Spaces \longrightarrow Invariant Groups

- **Kenzo**
 - Computer Algebra system devoted to Algebraic Topology implemented in *Common Lisp*
 - Homology groups which have not been obtained by other means
- **fKenzo**
 - *fKenzo*: graphical user interface for the system *Kenzo*
 - It is not necessary to be an expert in Algebraic Topology or Common Lisp to use it
 - Provides new functionalities to Kenzo such as the homology computation for digital images

Algebraic Topology

Goal

Formalize the analysis of monochromatic digital images

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Context

To deal with biomedical images:

- Reliability
- Efficiency

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Our approach

Formalize a technique to reduce the size of the information about a biomedical image (preserving its homological properties)

Goal

Verification
Algebraic Topology } + { Digital images } → Formalization of Digital Topology

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Verification
Algebraic Topology } + { Digital images } → Formalization of Digital Topology

The 95% of this thesis is devoted to formal verification

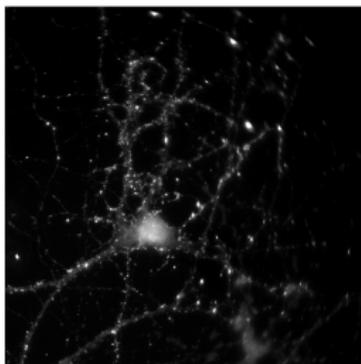
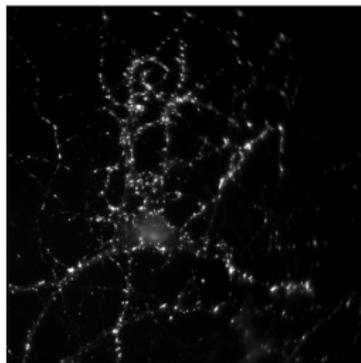
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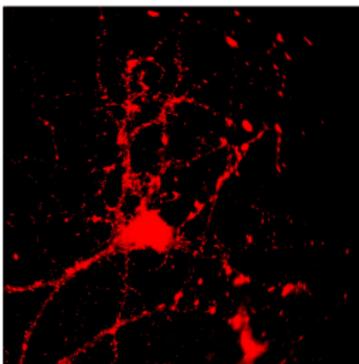
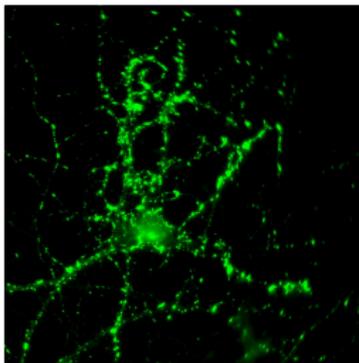
Biomedical Problem: counting synapses

- *Synapses* are the points of connection between neurons
- *Relevance*: Computational capabilities of the brain
- Procedures to modify the synaptic density may be an important asset in the treatment of neurological diseases, such as Alzheimer

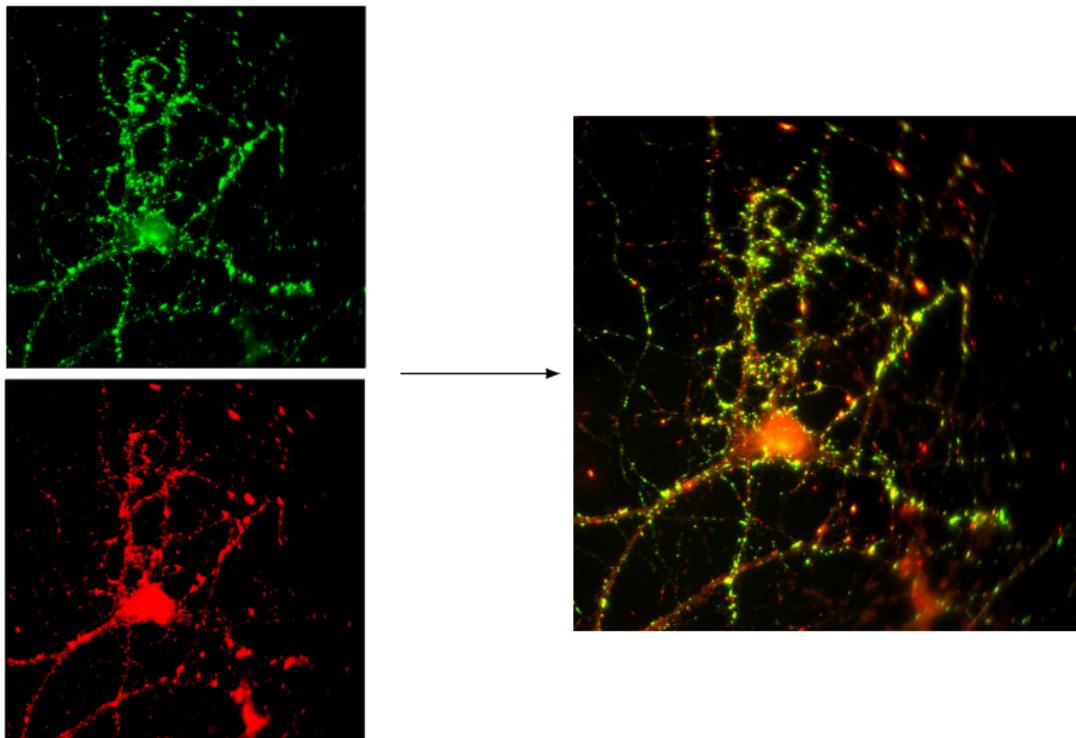
Manual process to count synapses



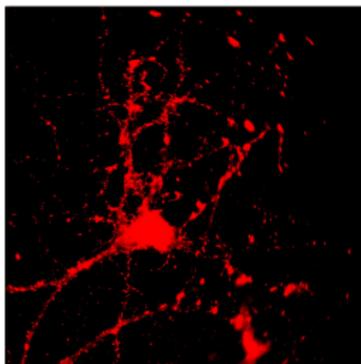
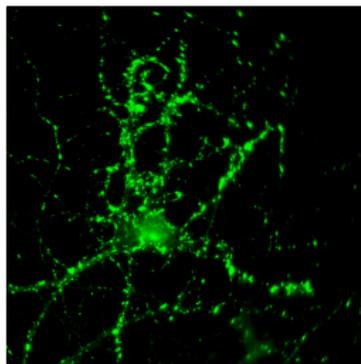
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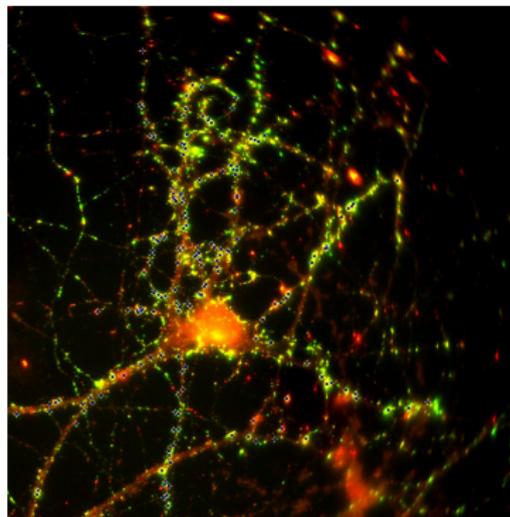
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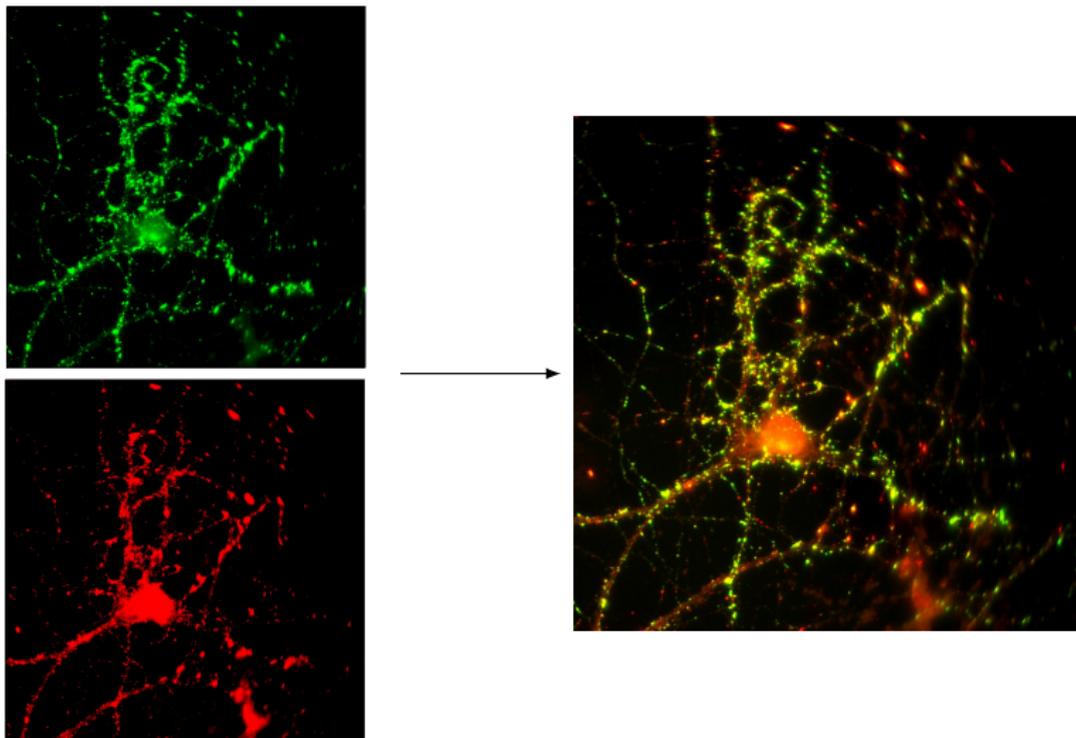
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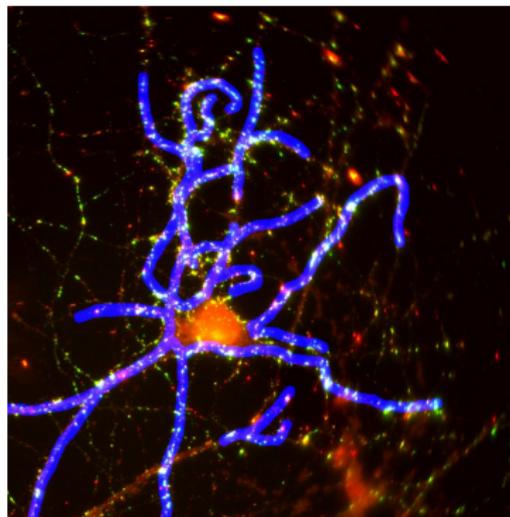
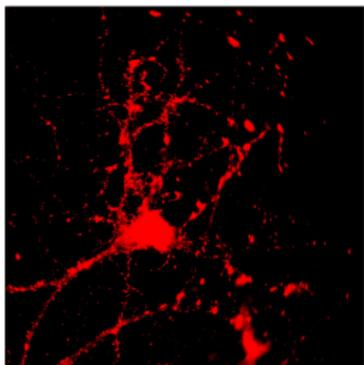
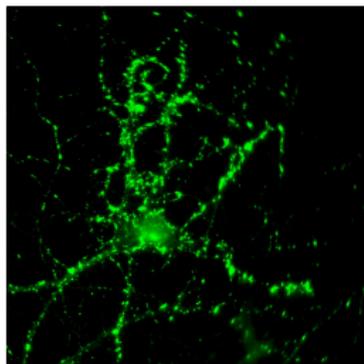
Count the synapses manually



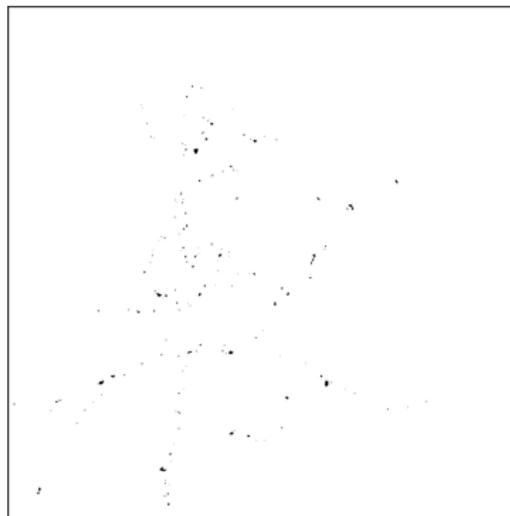
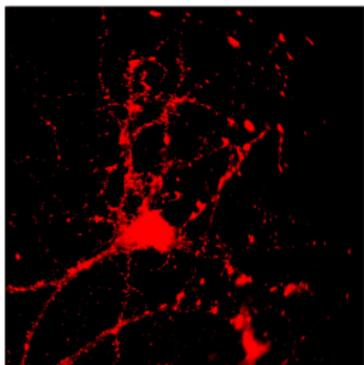
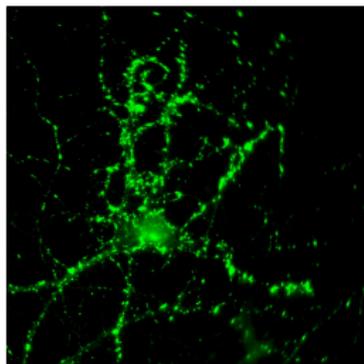
Semiautomatic process to count synapses



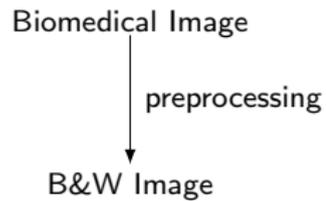
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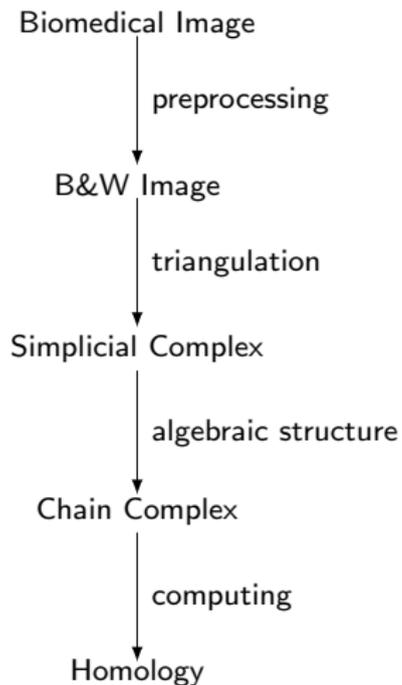
Semiautomatic process to count synapses



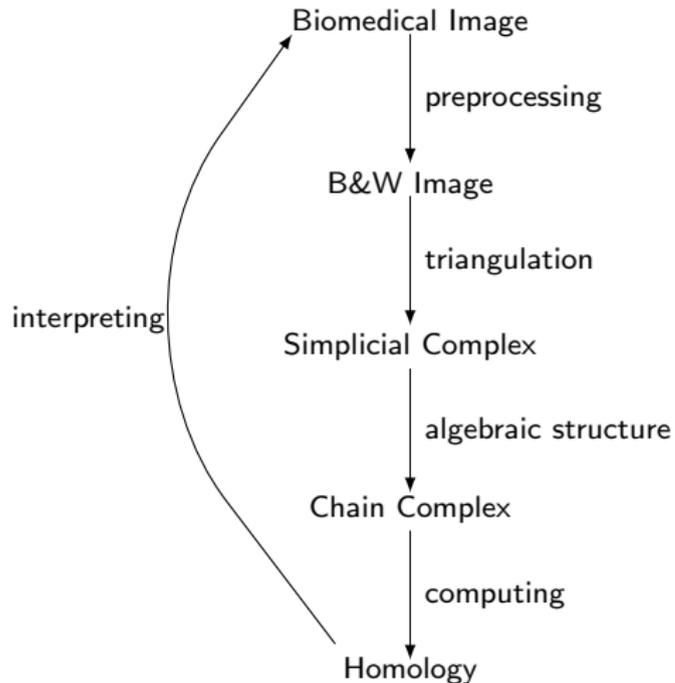
The method



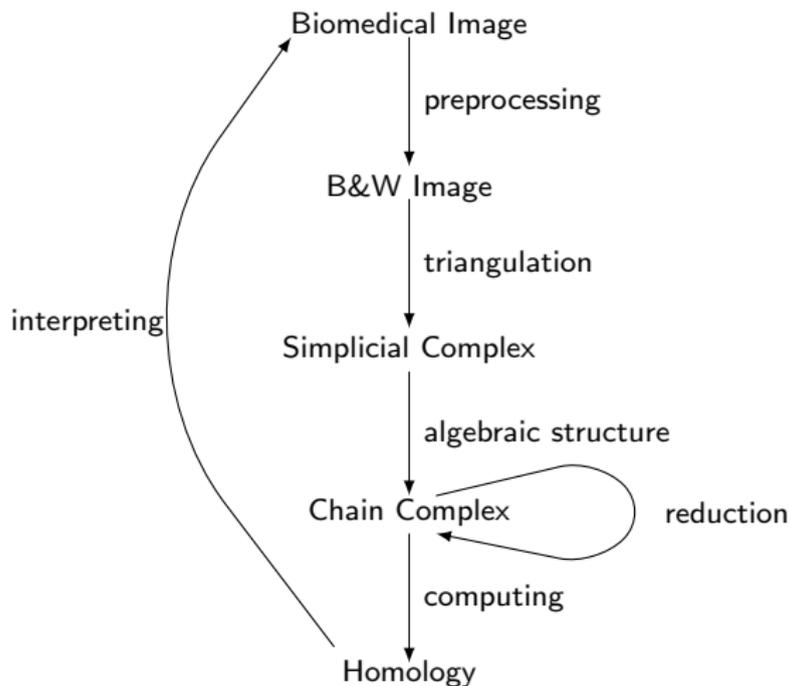
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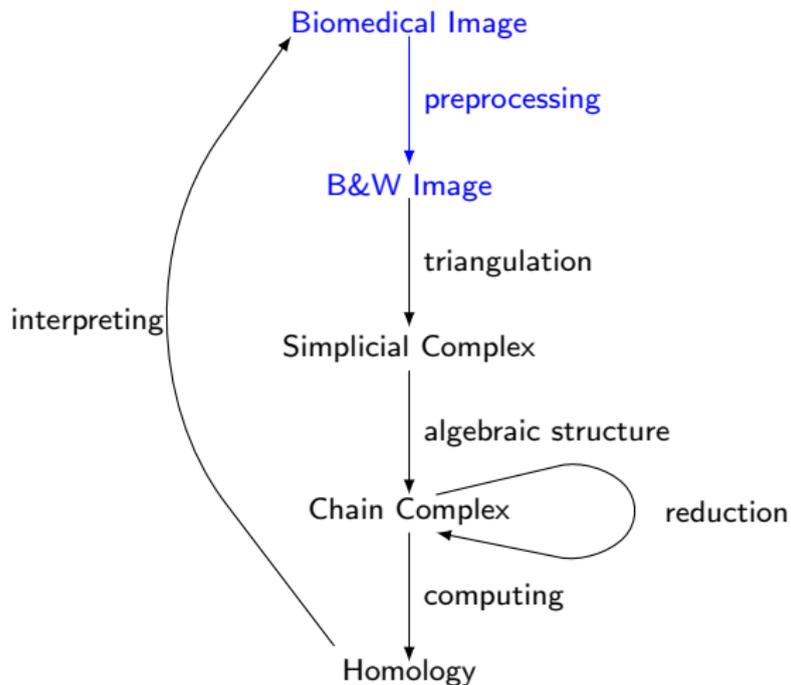
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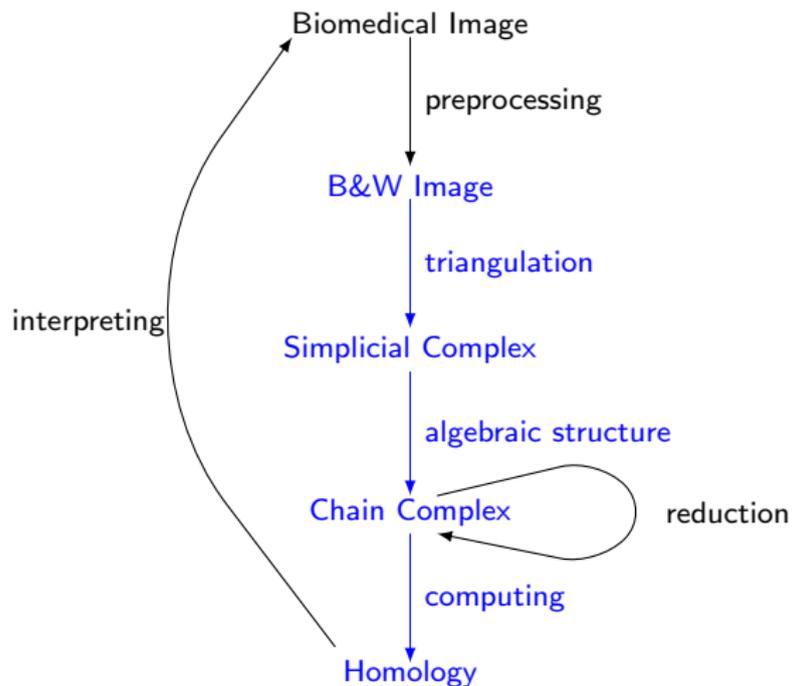
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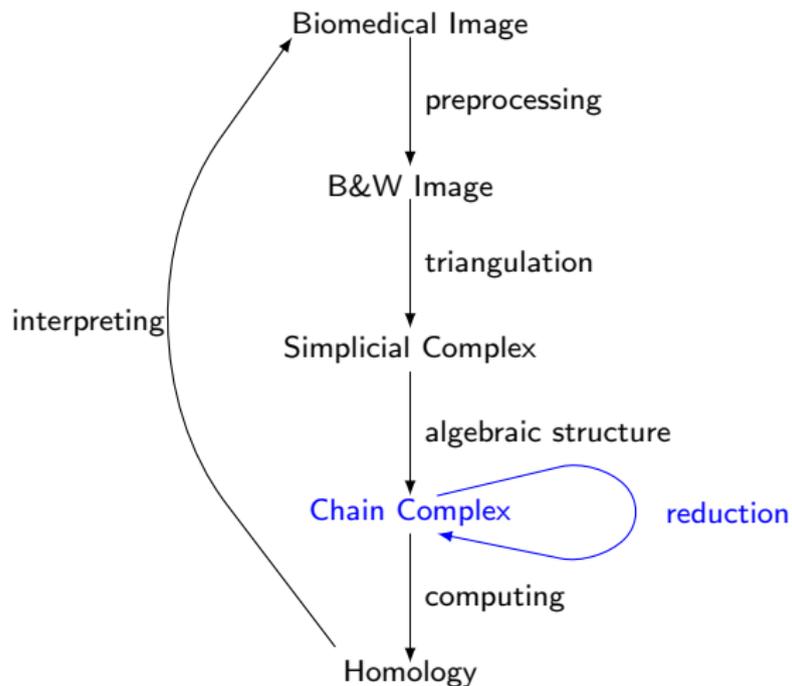
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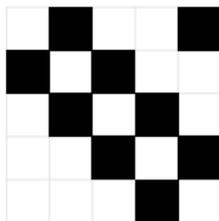


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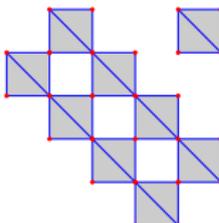
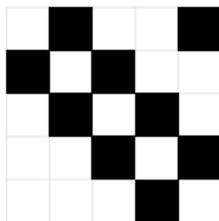
Digital Algebraic Topology

Digital Image



Digital Algebraic Topology

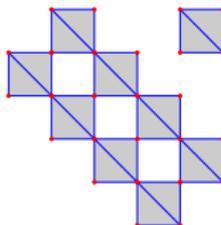
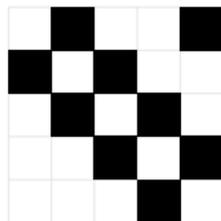
Digital Image



Simplicial Complex

Digital Algebraic Topology

Digital Image



Simplicial Complex

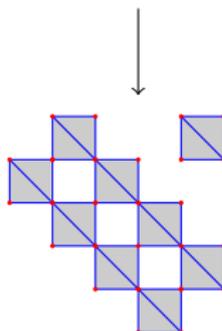
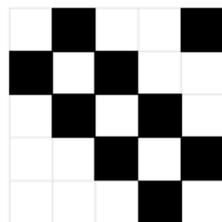


$C_0 =$ vertices
 $C_1 =$ edges
 $C_2 =$ triangles

Chain Complex

Digital Algebraic Topology

Digital Image



Simplicial Complex

Homology Groups

$$H_0 = \mathbb{Z} \oplus \mathbb{Z}$$

$$H_1 = \mathbb{Z} \oplus \mathbb{Z} \oplus \mathbb{Z}$$

$$C_0 = \text{vertices}$$

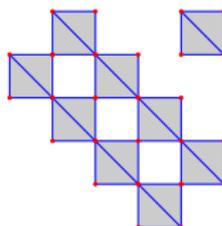
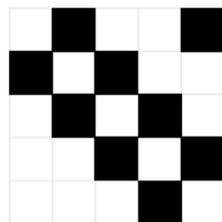
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Chain Complex

Digital Algebraic Topology

Digital Image



Simplicial Complex

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Chain Complex



Simplicial Complex

Definition

Let V be a set, called the vertex set, a *simplex* over V is any finite subset of V

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Variable V : finType.

Definition simplex := {set V}.

Definition simplicial_complex (c : {set simplex}) :=
forall x, x \in c -> forall y : simplex, y \subseteq x -> y \in c.

Chain Complex

Definition

A chain complex C_* is a pair of sequences $C_* = (C_q, d_q)_{q \in \mathbb{Z}}$ where:

- For every $q \in \mathbb{Z}$, the component C_q is a R -module, the chain group in degree q
- For every $q \in \mathbb{Z}$, the component d_q is a morphism $d_q : C_q \rightarrow C_{q-1}$, the differential function
- For every $q \in \mathbb{Z}$, the composition $d_q d_{q+1}$ is null: $d_q d_{q+1} = 0$

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Definition

Let \mathcal{K} be a finite simplicial complex, $C_n(\mathcal{K})$ is a free module and the n -simplices of \mathcal{K} form the standard basis of it. Then, given an order, for all n we can represent the differential map $d_n : C_n(\mathcal{K}) \rightarrow C_{n-1}(\mathcal{K})$ relative to the standard basis of the chain groups as a \mathbb{Z}_2 matrix. Such a matrix is called the n -th *incidence matrix* of a simplicial complex.

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Definition incidenceMatrix :=

```
\matrix_(i < m, j < n)
```

```
if (nth set0 Left i) \in (boundary (nth set0 Top j)) then 1 else 0:
  bool.
```

Definition incidence_mx_n :=

```
incidenceMatrix (enum n_1_simplices)(enum n_simplices).
```

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Theorem `incidence_matrices_sc_product`:

```
forall (V:finType) (n:nat) (sc: {set (simplex V)}),
simplicial_complex sc ->
(incidence_mx_n sc n) *m (incidence_mx_n sc (n.+1)) = 0.
```

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J. Heras, M. Poza, M. Dénès and L. Rideau. Incidence simplicial matrices formalized in COQ/SSREFLECT, Proceedings 18th Symposium on the Integration of Symbolic Computation and Mechanised Reasoning (Calculemus'11), Lecture Notes in Computer Science, vol. 6824, pages 30-44, 2011.

Homology

Definition

If $C_* = (C_q, d_q)_{q \in \mathbb{Z}}$ is a chain complex:

- The image $B_q = \text{im } d_{q+1} \subseteq C_q$ is the (sub)module of q -boundaries
- The kernel $Z_q = \text{ker } d_q \subseteq C_q$ is the (sub)module of q -cycles

Definition

Let $C_* = (C_q, d_q)_{q \in \mathbb{Z}}$ be a chain complex. For each degree $n \in \mathbb{Z}$, the n -homology module of C_* is defined as the quotient module

$$H_n(C_*) = \frac{Z_n}{B_n}$$

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```
Variable (K : fieldType) (V1 V2 V3 : vectType K)
  (f : linearApp V1 V2) (g : linearApp V2 V3).
Definition Homology := ((lker g) :\ (limg f)).
```

Homology

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Definition $\text{dim_homology } (\text{mxf} : 'M[K]_{(v1, v2)}) (\text{mxg} : 'M[K]_{(v2, v3)}) := v2 - \text{\rank mxg} - \text{\rank mxf}.$

Lemma $\text{dimHomologyrankE} : \text{mxf} * \text{m mxg} = 0 \rightarrow \text{\dim Homology (LinearApp mxf) (LinearApp mxg)} = \text{dim_homology mxf mxg}.$

Homology

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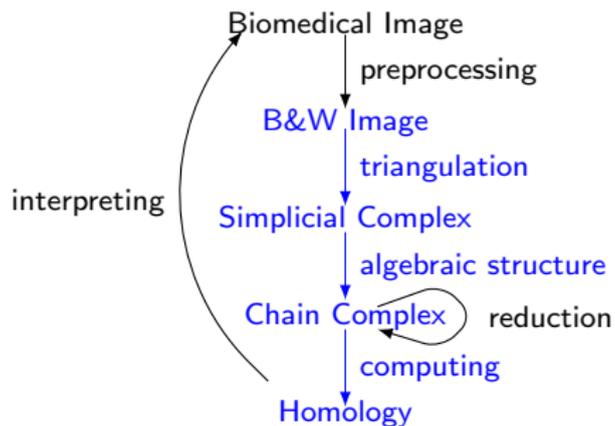
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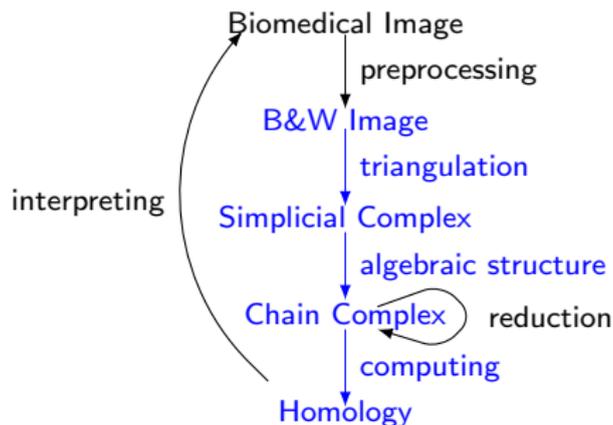


J. Heras, M. Dénès, G. Mata, A. Mörtberg, M. Poza and V. Siles. Towards a certified computation of homology groups for digital images, Proceedings 4th International Workshop on Computational Topology in Image Context (CTIC'12), Lecture Notes in Computer Science, vol. 7309, pages 49-57, 2012.

Summary and problems

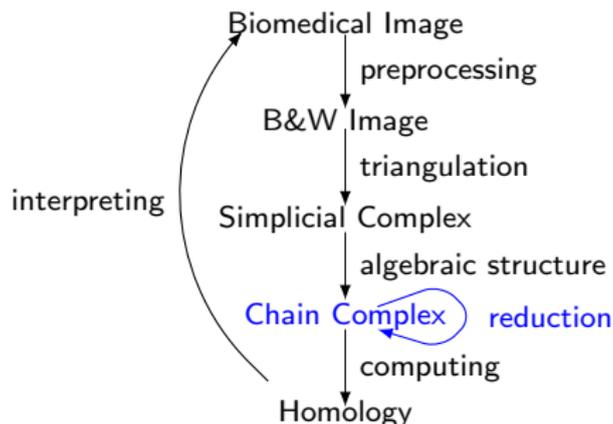


Summary and problems



- This process can be applied to any digital image
 - Reliability

Summary and problems



- This process can be applied to any digital image
 - Reliability
- Biomedical images:
 - Reliability
 - Efficiency: size of the images
- Solution to our approach to the tackle the efficiency problem

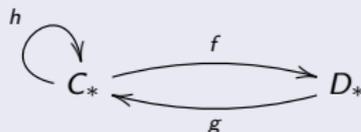
Table of Contents

- 1 Introduction
- 2 Biomedical images and certified software
- 3 Reduction procedure**
- 4 Methodology and experimental aspects
- 5 Conclusions and further work

Reduction

Definition

A reduction ρ between two chain complexes C_* y D_* (denoted by $\rho : C_* \Rightarrow D_*$) is a triple $\rho = (f, g, h)$



satisfying the following relations:

- 1) $fg = id_{D_*}$;
- 2) $d_{C_*} h + h d_{C_*} = id_{C_*} - gf$;
- 3) $fh = 0$; $hg = 0$; $hh = 0$.

Theorem

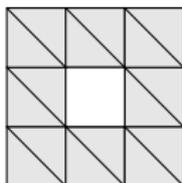
If $C_* \Rightarrow D_*$, then $C_* \cong D_* \oplus A_*$, with A_* acyclic, this implies that $H_n(C_*) \cong H_n(D_*)$ for all n .

Discrete Vector Fields: intuitive idea

- Reduce the amount of information but keeping the homological properties
- Discrete Morse Theory
 - Vector fields are a tool to cancel “useless” information

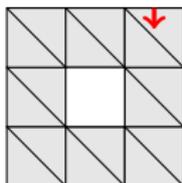
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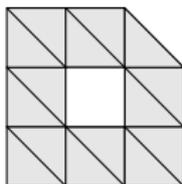
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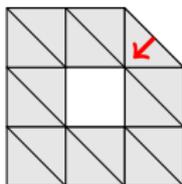
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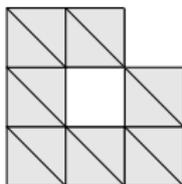
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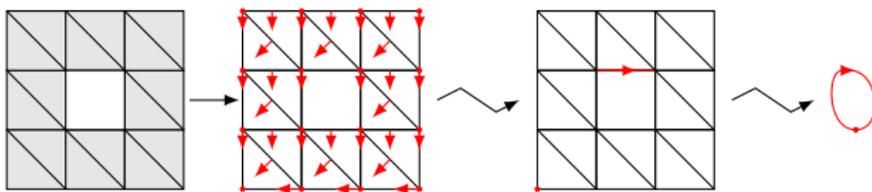
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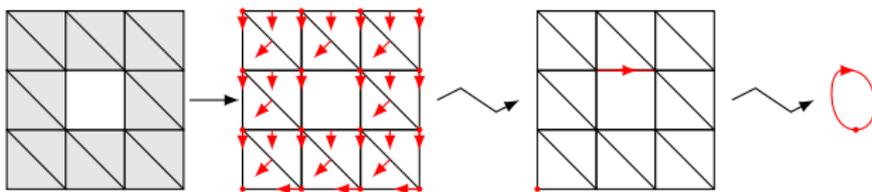
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Discrete Vector Fields: intuitive idea

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 - Vector fields are a tool to cancel “useless” information



$$\begin{array}{ccccccc}
 0 & \leftarrow & \mathbb{Z}^{16} & \xleftarrow{d_1} & \mathbb{Z}^{32} & \xleftarrow{d_2} & \mathbb{Z}^{16} \leftarrow 0 \\
 & & & \downarrow & & & \\
 0 & \leftarrow & \mathbb{Z} & \xleftarrow{\hat{d}_1} & \mathbb{Z} & \xleftarrow{\hat{d}_2} & 0 \leftarrow 0
 \end{array}$$

Discrete Vector Fields

Definition

Let $C_* = (C_p, d_p)_{p \in \mathbb{Z}}$ be a free chain complex with distinguished \mathbb{Z} -basis $\beta_p \subset C_p$. A $(p-1)$ -cell σ is a *face* of a p -cell τ if the coefficient of σ in $d\tau$ is non-null. It is a *regular face* if this coefficient is $+1$ or -1 .

Definition

A *discrete vector field* on C_* is a collection of pairs $V = \{(\sigma_i, \tau_i)\}_{i \in \beta}$ satisfying the conditions:

- 1 Every σ_i is some element of β_p , in which case the other corresponding component $\tau_i \in \beta_{p+1}$. The degree p depends on i and in general is not constant
- 2 Every component σ_i is a *regular face* of the corresponding component τ_i
- 3 A generator of C_* appears at most one time in V

Discrete Vector Fields

Definition

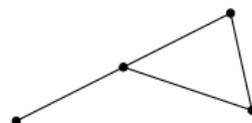
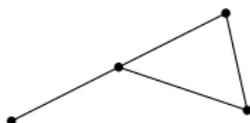
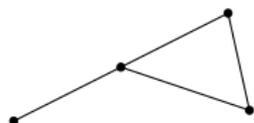
A V -path of degree p is a sequence $\pi = ((\sigma_{i_k}, \tau_{i_k}))_{0 \leq k < m}$ satisfying:

- 1 Every pair $((\sigma_{i_k}, \tau_{i_k}))$ is a component of V and the cell τ_{i_k} is a p -cell
- 2 For every $0 < k < m$, the component σ_{i_k} is a face of $\tau_{i_{k-1}}$, non necessarily regular, but different from $\sigma_{i_{k-1}}$

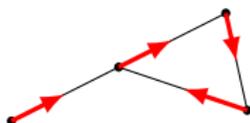
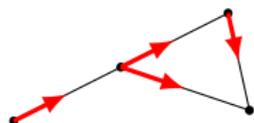
Definition

A discrete vector field V is *admissible* if for every $p \in \mathbb{Z}$, a function $\lambda_p : \beta_p \rightarrow \mathbb{Z}$ is provided satisfying the property: every V -path starting from $\sigma \in \beta_p$ has a length bounded by $\lambda_p(\sigma)$.

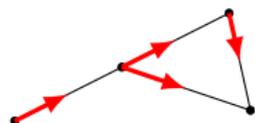
Example: an admissible discrete vector field



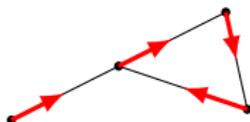
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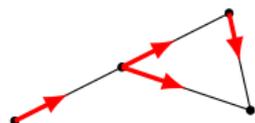
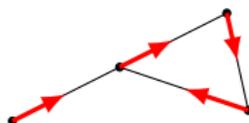
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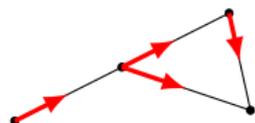
Dvf x



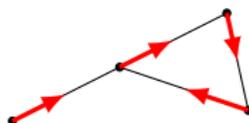
Example: an admissible discrete vector field

Dvf \times Dvf \checkmark Admissible \times 

Example: an admissible discrete vector field



Dvf x



Dvf ✓

Admissible x



Dvf ✓

Admissible ✓



Discrete Vector Fields

Definition

A cell χ which does not appear in a discrete vector field $V = \{(\sigma_i, \tau_i)\}_{i \in \beta}$ is called a *critical cell*.

Vector-Field Reduction Theorem

Let $C_* = (C_p, d_p, \beta_p)_p$ be a free chain complex and $V = \{(\sigma_i, \beta_i)\}_{i \in \beta}$ be an admissible discrete vector field on C_* . Then the vector field V defines a canonical reduction $\rho = (f, g, h) : (C_p, d_p) \implies (C_p^c, d_p')$ where $C_p^c = \mathbb{Z}[\beta_p^c]$ is the free \mathbb{Z} -module generated by the critical p -cells.



A. Romero and F. Sergeraert. Discrete Vector Fields and Fundamental Algebraic Topology, 2010. <http://arxiv.org/abs/1005.5685v1>.

Vector fields and matrices

Differential maps of a chain complex of finite type can be represented as matrices

$$\dots \leftarrow \mathbb{Z}_2^m \xleftarrow{M} \mathbb{Z}_2^n \leftarrow \dots$$

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Definition

An admissible discrete vector field V for M is nothing but a set of integer pairs $\{(a_i, b_i)\}$ satisfying these conditions:

- 1 $1 \leq a_i \leq m$ and $1 \leq b_i \leq n$
- 2 The entry $M[a_i, b_i]$ of the matrix is 1
- 3 The indices a_i (resp. b_i) are pairwise different
- 4 Non existence of loops

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- 3 The indices a_i (resp. b_i) are pairwise different
- 4 Non existence of loops

```
Definition admissible_dvf (M: 'M[Z2]_(m,n))
  (V: seq ('I_m * 'I_n)) (ords : simpl_rel 'I_m) :=
  all [pred p | M p.1 p.2 == 1] V &&
  uniq (map (@fst _ _) V) && uniq (map (@snd _ _) V) &&
  all [pred i | ~ (connect ords i i)] (map (@fst _ _) V).
```

Main algorithms

Algorithm

Input: A matrix M

Output: An admissible discrete vector field for M

Algorithm

Input: A chain complex C_ and an admissible discrete vector field of C_**

Output: A reduction from C_ to a reduced chain complex \hat{C}_**



A. Romero and F. Sergeraert. Discrete Vector Fields and Fundamental Algebraic Topology, 2010. <http://arxiv.org/abs/1005.5685v1>.

Romero-Sergeraert's Algorithm

Algorithm (The RS Algorithm)

Input: a matrix M with coefficients in \mathbb{Z} .

Output: an admissible discrete vector field V for M and a list of relations r .

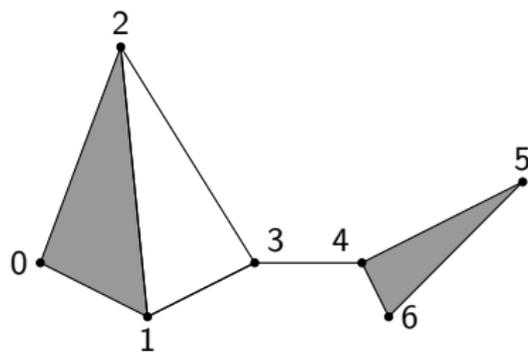
- 1 Initialize the vector field V to the void vector field and the relations r to empty.
- 2 For every row i of M :
 - 1 For every column j , which is different from the second components of V , such that $M[i, j] = 1$ or $M[i, j] = -1$:
 - Look for the rows $k \neq i$ such as $M[k, j] \neq 0$ and obtain the relations $i > k$. Then, build the transitive closure of r and these relations.

If there is no loop in that transitive closure:

then: Add (i, j) to V , let r be that transitive closure, and repeat from Step 2 with the next row.

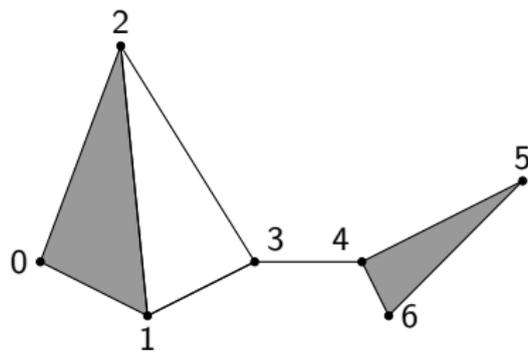
else: Repeat from Step 2.1. with the next column.

Example



$$\begin{array}{l}
 \{0\} \\
 \{1\} \\
 \{2\} \\
 \{3\} \\
 \{4\} \\
 \{5\} \\
 \{6\}
 \end{array}
 \begin{pmatrix}
 \{0,1\} & \{0,2\} & \{1,2\} & \{1,3\} & \{2,3\} & \{3,4\} & \{4,5\} & \{4,6\} & \{5,6\} \\
 1 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
 1 & 0 & 1 & 1 & 0 & 0 & 0 & 0 & 0 \\
 0 & 1 & 1 & 0 & 1 & 0 & 0 & 0 & 0 \\
 0 & 0 & 0 & 1 & 1 & 1 & 0 & 0 & 0 \\
 0 & 0 & 0 & 0 & 0 & 1 & 1 & 1 & 0 \\
 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 1 \\
 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 1
 \end{pmatrix}$$

Example



$$\begin{array}{l}
 \{0, 1\} \\
 \{0, 2\} \\
 \{1, 2\} \\
 \{1, 3\} \\
 \{2, 3\} \\
 \{3, 4\} \\
 \{4, 5\} \\
 \{4, 6\} \\
 \{5, 6\}
 \end{array}
 \begin{array}{cc}
 \{0, 1, 2\} & \{4, 5, 6\} \\
 \left(\begin{array}{cc}
 1 & 0 \\
 1 & 0 \\
 1 & 0 \\
 0 & 0 \\
 0 & 0 \\
 0 & 0 \\
 0 & 1 \\
 0 & 1 \\
 0 & 1
 \end{array} \right)
 \end{array}$$

Example

$$\begin{pmatrix} 1 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 1 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 1 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 1 \end{pmatrix}$$

① $\text{dvf} = \{\}, \text{orders} = \{\}$

Example

$$\begin{pmatrix} 1 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 1 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 1 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 1 \end{pmatrix}$$

- 1 $\text{dvf} = \{\}$, $\text{orders} = \{\}$
- 2 $\text{dvf} = \{(1, 1)\}$, $\text{orders} = \{1 > 2\}$

Example

$$\begin{pmatrix} 1 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 1 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 1 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 1 \end{pmatrix}$$

- 1 dvf = {}, orders = {}
- 2 dvf = {(1, 1)}, orders = {{1 > 2}}
- 3 dvf = {(1, 1), (2, 3)}, orders = {{1 > 2}, {2 > 3}}

Example

$$\begin{pmatrix} 1 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 1 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 1 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 1 \end{pmatrix}$$

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- 4 $\text{dvf} = \{(1, 1), (2, 3), (3, 5)\}$,
 $\text{orders} = \{\{1 > 2\}, \{2 > 3\}, \{3 > 4\}\}$
- 5 ...
- 6 $\text{dvf} = \{(1, 1), (2, 3), (3, 5), (4, 6), (5, 7), (6, 9)\}$
 $\text{orders} = \{\{1 > 2\}, \{2 > 3\}, \{3 > 4\}, \{4 > 5\}, \{5 > 6\}, \{6 > 7\}\}$

The abstract specification

```
Fixpoint genDvfOrders M V (ords : simpl_rel _) k :=
  if k is 1.+1 then
    let P := [pred ij | admissible (ij::V) M
              (relU ords (gen_orders M ij.1 ij.2))] in
    if pick P is Some (i,j)
      then genDvfOrders M ((i,j)::V)
              (relU ords (gen_orders M i j)) 1
    else (V, ords)
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```

```
Definition gen_adm_dvf M :=
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```

```

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```

```

Lemma admissible_gen_adm_dvf m n (M : 'M[Z2]_(m,n)) :
  let (vf,ords) := gen_adm_dvf M in admissible vf M ords.

```

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```

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  let (vf,ords) := gen_adm_dvf M in admissible vf M ords.

```

Problem

It is not an executable algorithm

Verifying the RS-algorithm

Definition `Z2 := Fp_fieldType 2.`

Record `matZ2:=`

```
{M:> seq (seq Z2);  
  m:nat;  
  n:nat;  
  is_matrix: M = [::] \/  
    [/\ m = size M & forall i, i < m -> size (rowseqmx M i) = n]  
}.
```

Definition `vectorfield:= seq (prod nat nat).`

Definition `rels:= seq (seq nat).`

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}.
```

Definition vectorfield:= seq (prod nat nat).

Definition rels:= seq (seq nat).

Definition Vecfieldadm (M: matZ2)(vf: vectorfield)(r:rels) :=

```
(all [pred i | 0<= i < (M m)](getfirstseq vf)) /\
(all [pred i | 0<= i < (M n)](getsndseq vf)) /\
(forall i j:nat, (i,j) \in vf -> (nth 0 (nth nil M i) j) = 1%R) /\
(uniq (getfirstseq vf)) /\
(uniq (getsndseq vf)) /\
(forall i j 1:nat, (i,j) \in vf -> i!=1
  -> (nth 0 (nth nil M 1) j) != 0%R -> (i::1::nil) \in r) /\
prop_cat2 r /\
(all uniq r) /\
(ordered glMax vf r).
```

Verifying the RS-algorithm

Theorem `dvfordisVecfieldadm (M:matZ2):
Vecfieldadm M (dvford M)(genOrders M).`

Verifying the RS-algorithm

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Lemma `v_in_genDvf_Mv1 (M: matZ2): (forall a b:nat,
((a,b) \in (dvford M)) -> nth 0 (nth nil M a) b = 1%R).`

Verifying the RS-algorithm

Theorem `dvfordisVecfieldadm (M:matZ2):
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Lemma `inDvf_compij1 (p a b:nat) (M : matZ2):
(a,b) \in (fst (genDvfOrders p 0 0 M M [::] [::]))
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Lemma `inDvf_compij1_general (p i j a b :nat) (M M2: matZ2)
(vf: vectorfield)(r: rels):
(forall k2, nth 0 (nth nil M (i + a)) k2 = nth 0 (nth nil M2 a) k2)
-> (i + a, j + b) \in fst (genDvfOrders p i j M M2 vf r)
-> nth 0 (nth nil M (i + a)) (j + b) = 1%R.`

Verifying the RS-algorithm

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The proofs detailed in this section involve 49 definitions and 109 lemmas. In general, the development takes up 3772 code lines.

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The proofs detailed in this section involve 49 definitions and 109 lemmas. In general, the development takes up 3772 code lines.



J. Heras, M. Poza and J. Rubio. Verifying an algorithm computing Discrete Vector Fields for digital imaging. Proceedings Conferences on Intelligence Computer Mathematics (CICM'12), Lecture Notes in Computer Science, vol. 7362, pages 215-229, 2012. <http://arxiv.org/abs/1005.5685v1>.

General idea of the Vector-Field Reduction Theorem

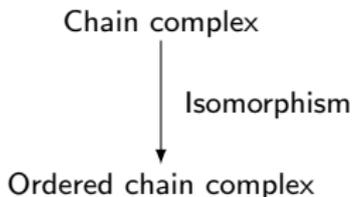
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General idea of the Vector-Field Reduction Theorem

Vector-Field Reduction Theorem

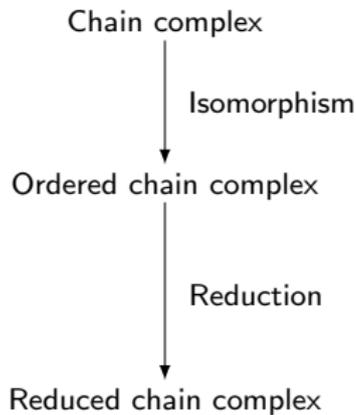
Let $C_* = (C_p, d_p, \beta_p)_p$ be a free chain complex and $V = \{(\sigma_i, \beta_i)\}_{i \in \beta}$ be an admissible discrete vector field on C_* . Then the vector field V defines a canonical reduction $\rho = (f, g, h) : (C_p, d_p) \implies (C_p^c, d_p')$ where $C_p^c = \mathbb{Z}[\beta_p^c]$ is the free \mathbb{Z} -module generated by the critical p -cells.



General idea of the Vector-Field Reduction Theorem

Vector-Field Reduction Theorem

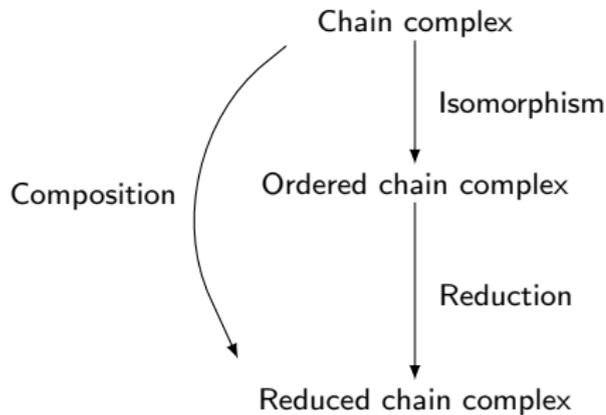
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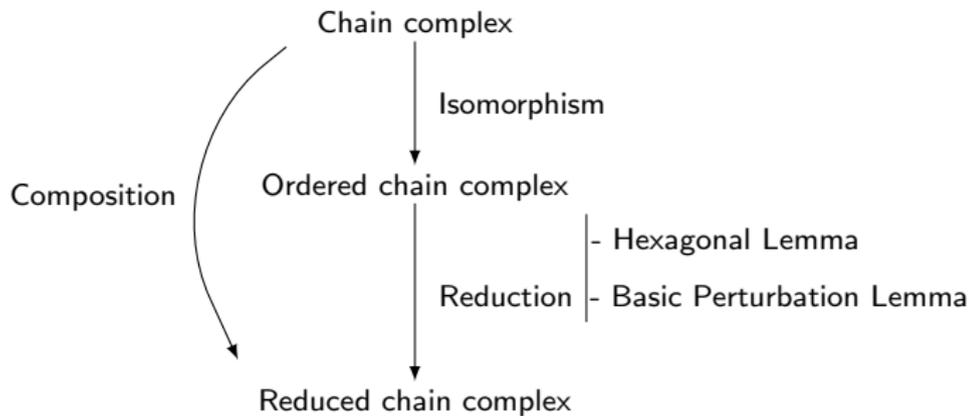
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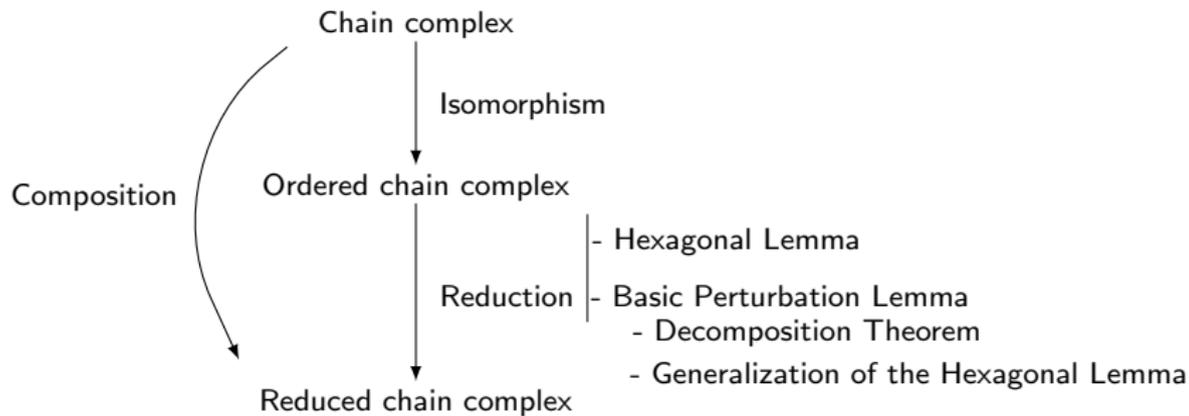
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Vector-Field Reduction Theorem using HL

Hexagonal Lemma

Let $C = (C_p, d_p)_p$ be a chain complex. For some $k \in \mathbb{Z}$, the chain groups C_k and C_{k+1} are given with decompositions $C_k = C'_k \oplus C''_k$ and $C_{k+1} = C'_{k+1} \oplus C''_{k+1}$, so that between the degrees $k-1$ and $k+2$ this chain complex is described by the diagram:

$$\begin{array}{ccccc}
 & & C''_k & \xleftrightarrow{\varepsilon^{-1}} & C''_{k+1} & & \\
 & \delta & \swarrow & & \searrow & \eta & \\
 & & C''_k & \xleftarrow{\varepsilon} & C''_{k+1} & & \\
 & & \vdots & \varphi & \vdots & & \\
 C_{k-1} & \xleftarrow{d} & \oplus & \xleftarrow{d} & \oplus & \xleftarrow{d} & C_{k+2} \\
 & \alpha & \swarrow & \psi & \searrow & \gamma & \\
 & & C'_k & \xleftarrow{\beta} & C'_{k+1} & &
 \end{array} \tag{1}$$

The partial differential $\varepsilon : C''_{k+1} \rightarrow C''_k$ is assumed to be an isomorphism. Then a canonical reduction can be defined $\rho : C \Rightarrow C'$ where C' is the same chain complex as C except between the degrees $k-1$ and $k+2$:

$$\dots \leftarrow C_{k-2} \leftarrow C_{k-1} \xleftarrow{\alpha} C'_k \xleftarrow{\beta - \psi \varepsilon^{-1} \varphi} C'_{k+1} \xleftarrow{\gamma} C_{k+2} \leftarrow C_{k+3} \leftarrow \dots$$

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 & & \oplus & \xleftarrow{d} & \oplus & \xrightarrow{d} & C_{k+2} \\
 & & \uparrow & \searrow & \uparrow & \swarrow & \\
 & \alpha & C'_k & \xleftarrow{\beta} & C'_{k+1} & \xrightarrow{\gamma} & \\
 & & \downarrow & \swarrow & \downarrow & \searrow & \\
 & & C_{k-1} & & C_k & &
 \end{array} \quad (1)$$

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Development: 303 definitions, 361 lemmas and 7511 lines

Basic Perturbation Lemma

Basic Perturbation Lemma (BPL)

Let us consider a reduction $\rho = (f, g, h) : C_* \rightrightarrows \widehat{C}_*$ between two chain complexes (C_*, d) and $(\widehat{C}_*, \widehat{d})$, and δ a perturbation of d . Furthermore, the composite function δh is assumed *locally nilpotent*. Then, a perturbation $\widehat{\delta}$ can be defined for the differential map \widehat{d} and a new reduction $\rho' = (f', g', h') : (C_*, d + \delta) \rightrightarrows (\widehat{C}_*, \widehat{d} + \widehat{\delta})$ can be constructed.

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J. Aransay, C. Ballarín and J. Rubio. A mechanized proof of the Basic Perturbation Lemma, *Journal of Automated Reasoning*, volume 40-4, pages 271-292, 2008.

- A particular case of the BPL was also proved in Coq using bicomplexes.



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Goal

A formalization of the general case in SSREFLECT with finitely generated structures.

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Variable K : fieldType.

Variable ρ : FGReduction K .

Variable δ : forall $i:Z$, 'M[K]_(m (C rho)(i+1), m (C rho) i).

Hypothesis boundary_dp : forall $i:Z$,
 $((\text{diff } (C \text{ rho})(i+1) + \delta (i+1)) * m ((\text{diff } (C \text{ rho})i + \delta i) = 0.$

Variable (n : nat).

Hypothesis nilpotency_hp : forall $i:Z$,
 $(\text{pot_matrix } (\delta i * m (\text{Ho } (H \text{ rho}) i)) n = 0).$

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((diff (C rho)(i+1) + delta (i+1)) *m ((diff (C rho)i + delta i) = 0.

Variable (n : nat).

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(pot_matrix (delta i *m (Ho (H rho) i)) n = 0).

Definition quasi_bpl :=

(rhoHL (Di := Di_pert) (boundary_Di := boundary_dp_new)
inverse_dp_12_inverse).

Basic Perturbation Lemma

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- Development

- 63 definitions
- 117 lemmas
- 2416 lines



M. Poza, C. Domínguez, J. Heras, and J. Rubio. A certified reduction strategy for homological image processing. Submitted, 2013, <http://www.unirioja.es/cu/cedomin/crship/>

Key aspects of the formalization

- The role of `SSREFLECT`
- Different representations
- Casts
- Dealing with kernels

The role of SSREFLECT

- Libraries:

- matrix.v: theory matrix, determinant, matrix decomposition,...

$$d'_1 * d'_2 = 0 \rightarrow \left(\begin{array}{c|c} \varepsilon & \varphi \\ \psi & \beta \end{array} \right) * \left(\begin{array}{c} \eta \\ \gamma \end{array} \right) = 0. \text{ Therefore,}$$

- $\varepsilon * \eta + \varphi * \gamma = 0$ which implies that $\varphi * \gamma = -\varepsilon * \eta$
- $\psi * \eta + \beta * \gamma = 0$

Definition `block_mx Aul Aur Adl Adr : 'M_(m1 + m2, n1 + n2) := col_mx (row_mx Aul Aur) (row_mx Adl Adr).`

The role of SSREFLECT

- Libraries:

- `matrix.v`: theory matrix, determinant, matrix decomposition...
- `finset.v` and `fintype.v`

Variable `V` : `finType`.

Definition `simplex` := `{set V}`.

Definition `simplicial_complex` (`c` : `{set simplex}`) :=
 `forall` `x`, `x \in c` -> `forall` `y` : `simplex`, `y \subset x` -> `y \in c`.

The role of SSREFLECT

- Libraries:
 - `matrix.v`: theory matrix, determinant, matrix decomposition...
 - `finset.v` and `fintype.v`
 - `bigop.v`

$$\sum_{i \in r | P_i} F_i = \sum_{i \in r | P_i \wedge a_i} F_i + \sum_{i \in r | P_i \wedge \sim a_i} F_i$$

- ...

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- ...
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- ...
- Efficiency when writing of proofs
- Definitions are blocked not to be expanded during type checking
- Definitions lack direct effective computation

Two SSREFLECT matrix representations

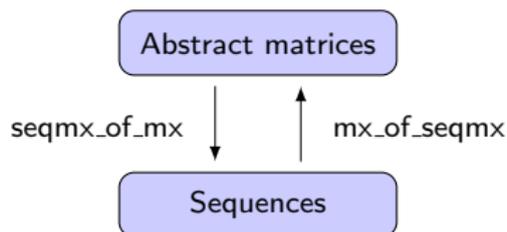
- As functions
 - Definition of different operations and proved properties about them
 - Not directly executable
- As sequences of sequences
 - Operations can be executed
 - Prove properties is much harder
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Conclusions

To compute \mapsto Sequences
To prove \mapsto Abstract matrices



Chain complexes representations

The chain complex associated with a simplicial complex related to a 2D image

$$\dots \leftarrow 0 \leftarrow 0 \leftarrow C_0 \xleftarrow{d_1} C_1 \xleftarrow{d_2} C_2 \leftarrow 0 \leftarrow 0 \leftarrow \dots$$

A *truncated* chain complex is

$$C_0 \xleftarrow{d_1} C_1 \xleftarrow{d_2} C_2$$

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Definition `is_chaincomplex (d1 d2: matZ2) (m n p: nat):=`
`is_matrix m n d1 /\`
`is_matrix n p d2 /\`
`(mx_of_seqmx m n d1) *m (mx_of_seqmx n p d2) = 0.`

Record `chaincomplex:=`
`{d1: matZ2;`
`d2: matZ2;`
`m: nat;`
`n: nat;`
`p: nat;`
`chaincomplex_proof: is_chaincomplex d1 d2 m n p}.`

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A *truncated* chain complex is

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Variable `K` : fieldType.

Record `FGChain_Complex` :=

```
{ m : Z -> nat;
  diff : forall i:Z, 'M[K]_(m (i + 1), m i);
  boundary : forall i:Z, (diff (i + 1)) *m (diff i) = 0}.
```

Casts

There exists a rigid typing strategy in Coq

$$M_i \not\Rightarrow M_{(i+1-1)}$$

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 Then, $d_{i+1}h_i : C_i \rightarrow C_{i+1-1} \quad 'M_{(m \ C \ i, \ m \ C \ (i+1-1))} \not\Rightarrow 'M_{(m \ C \ i)}$

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Lemma cast1: $m \ C \ i = m \ C \ i$.

Lemma cast2: $m \ C \ (i+1-1) = m \ C \ i$.

castmx (cast1, cast2) ((Ho H i) *m (diff C (i+1)))

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castmx (cast1, cast2) ((Ho H i) *m (diff C (i+1)))

Re-indexing structures

If $d_j : C_{j+1} \rightarrow C_j$ then $d_{j+1}h_j : C_j \rightarrow C_j$ and the obtained matrix is $'M_{(m \ C \ i)}$.

Notations

An *n-suspended up* or *n-suspended down* chain complex for a chain complex is built moving up or down n degrees of a chain complex.

Dealing with kernels

Decomposition Theorem

Let $\rho = (f, g, h) : (C_*, d) \Rightarrow (\widehat{C}_*, \widehat{d})$ be a reduction. This reduction is equivalent to a decomposition: $C_* = A_* \oplus B_* \oplus C'_*$ where $A_* = \ker f \cap \ker h$, $B_* = \ker f \cap \ker d$ and $C'_* = \text{im } g$.

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The kernel of a finite map is defined by the kernel of the matrix which represents this map.

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The kernel of a finite map is defined by the kernel of the matrix which represents this map.

Definition `kermx m n (A : 'M_(m,n)) : 'M_m :=
 copid_mx (\rank A) *m invmx (col_ebase A).`

Lemma `mulmx_ker m n (A : 'M_(m, n)) : kermx A *m A = 0.`

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● Drawbacks

- The kernel consists of the elements that are made null when they are applied to the left
- It is necessary to work with transposed matrices
- The product is reversed
- Only *partial* identities are obtained

● Advantages

- Some useful lemmas about `kermx` are already proven in the `SSREFLECT` library

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Definition `ker_min (m n : nat) (M : 'M_(m,n)) :=
 (castmx ((Logic.eq_refl (m-\rank M)), (\rank M) + (m-(\rank M))) = m)
 (row_mx (@const_mx _ (m-\rank M) (\rank M) 0) 1%:M)) *m (kermx M).`

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Lemma `ker_min_kermx (m n : nat) (M : 'M_(m,n)) :
 (kermx M :=: (ker_min M))%MS.`

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- 1 Introduction
- 2 Biomedical images and certified software
- 3 Reduction procedure
- 4 Methodology and experimental aspects**
- 5 Conclusions and further work

Methodology

Goal

A methodology to verify a software program which smooths the “steep learning curve”

- 1 Implement a version of our algorithms in Haskell
- 2 Test properties about the Haskell programs
- 3 Verify the programs using `COQ` and its `SSREFLECT` library

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Advantages of Haskell

- Both the code and the way of working are similar to the ones in COQ
- The clean semantics of purely functional languages
- Haskell functions often satisfy simple algebraic properties
- Provides a profiling system
 - Where the system wastes time
 - Which parts of the proof should be improved
 - Data structures are suitable

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Testing

Goal: The testing process can be useful in order to detect bugs

- Manual testing
 - Small images
 - Very tedious and requires a lot of time

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Testing

Goal: The testing process can be useful in order to detect bugs

- Manual testing
- Automated testing
 - Use fKenzo
 - File with a battery of pairs of matrices (2D images randomly generated)
 - Compute homology
 - Use Haskell
 - Compute homology in Haskell with or without applying a reduction process

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Goal: The testing process can be useful in order to detect bugs

- Manual testing
- Automated testing

Study over 250 images	d1	d2
% of reduction	98	49

Methodology

Goal

A methodology to verify a software program which smooths the “steep learning curve”

- 1 Implement a version of our algorithms in Haskell
- 2 Test properties about the Haskell programs
- 3 Verify the programs using COQ and its SSREFLECT library

Testing

Goal: The testing process can be useful in order to detect bugs

- Manual testing
- Automated testing
- QuickCheck
 - A specification of the properties which must be satisfied by our programs is given
 - Testing the properties included in the specification

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This step is **not enough** to ensure that a program is correct

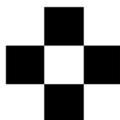
Alternatives in the methodology

- Efficiency: Haskell is a programming language
- Reliability: we are not sure of the correctness of our programs

Haskell as an oracle

The heavy computations are done in Haskell and then the properties of the output of the computation are proved in `SSREFLECT`

Computing over digital images



	<i>Haskell</i>	<i>SSReflect</i>
<i>Without advf</i>	0.06	0.46
<i>With advf</i>	0.046875	1.016

- We can compute in both systems

Computing over digital images



		<i>Haskell</i>	<i>SSReflect</i>
<i>Without advf</i>		0.9	9
<i>With advf</i>	Computation advf	2.484	101
	Ordered matrices	0	14
	Reduced matrix d_1	0	*
	Reduced matrix d_2	0.0624	5
	H_0 and H_1	1.252	3
Total		3.9	139

- `SSREFLECT` cannot compute the inverse of a matrix 64×64

Computing over digital images



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- Haskell as an oracle:
 - Compute the admissible discrete vector field and reorder the matrix in Coq
 - The top-left block `u1M` is extracted to Haskell and the inverse matrix is returned `invmx_u1M`
 - Prove in Coq:
 - The inverse of a matrix is unique
 - $\forall M, MM^{-1} = \text{id} \Rightarrow M^{-1}M = \text{id}$

```

Lemma m_invmxm : (mulseqmx u1M invmx_u1M)
  == (scalar_seqmx 64 (Ordinal (ltn_pmod 1 (ltn0Sn 1))))).
  
```

Computing over digital images



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- The RS algorithm is not necessary
- We can compute the dimension of the homology groups with the direct method

Computing over biomedical images

Biomedical context

Counting the number of synapses in a neuron



Problem

- SSREFLECT cannot compute the homology directly

Computing over biomedical images

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Goal

Obtain the H_0 by means of a certified process

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Goal

Obtain the H_0 by means of a certified process

- 1 Computing in Haskell the reduced matrix M_{red} and the components f_0 , f_1 , g_0 , g_1 and h_0 which define a 2-truncated reduction
- 2 Transform the matrices to `COQ/SSREFLECT`
- 3 Prove in `COQ/SSREFLECT` that these matrices establish a reduction
- 4 Compute H_0 from the reduced matrix M_{red} in `COQ/SSREFLECT`

Computing over biomedical images

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		<i>Haskell (min)</i>	<i>SSReflect</i>
<i>Without advf</i>		0.68	Not available
<i>With advf</i>	Computation advf	108	Proofs 12h 4min 55sec
	Reduced matrices	26	
	H_0	0.012	5sec
	Total	130	12h 5min

- We need to use the reduction method to obtain H_0 in a reliable way
- The matrix 743×1424 is reduced to 59×740

Sources of inefficiency

- Data types in languages of functional programming
 - Matrices
- Use of simplicial complexes instead of cubical complexes
- Execution inside the proof assistant
- Coq is a Proof Assistant and not a Computer Algebra system
- Concrete algorithms
 - Kenzo (ad-hoc algorithm to compute an admissible discrete vector field)
 - Heuristic techniques
- Proving needs more redundancy in algorithms

Table of Contents

- 1 Introduction
- 2 Biomedical images and certified software
- 3 Reduction procedure
- 4 Methodology and experimental aspects
- 5 Conclusions and further work**

Conclusions

- Development effort
- The implementation in `COQ/SSREFLECT` of the RS algorithm

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Further work

- Efficiency issues
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Certifying homological algorithms to study biomedical images*

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